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Energy Monitoring and Control Using New Linearized Power Flow Technique.

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ENERGY MONITORING AND CONTROL USING NEW LINEARIZED POWER FLOW TECHNIQUE

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Abstract

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The paper presents a proposed technique with linearized formula for computing the transmission line power flow in terms of injected power due to any change in power system loading conditions. The formula relates the line power flows to both loads and power generation directly for a transmission
network configuration. Being in an integral form, new power
flows on the lines can be obtained directly without running a complete load flow programs when the total system generation changes. This formula is a fairly general one as it is suitable for various energy monitoring and control applications such as generation shifts to alleviate the line overloads, the generation redispatch for an incremental change in loading conditions and the on-line load shedding programs as well as the fast contingency analysis.

INTRODUCTION

Among the major requirements placed upon security monttoring and control of bulk power systems are those of maintaining highly secure operation of interconnected system to prevent separation and failure of the system. Of the main functions of security monitoring and control is to maintain the active power flow in each line of the transmission network to be within a specified limits under the continuous changes is loading
conditions and the possible outage of any loaded transmission
lines. For such studies, the utility industry prefers faster
approximate techniques to locate the poten However, among the various approximate techniques, the relative accuracy is still of major importance to reflect analytically the magnitude of potentially dangerous everloads as really occurs as possible.

The use of genelity methods in system security and
contingency analysis remained very popular (1-4). The linearized
distribution factors was presented by MacArthur [5] and the
mathematical setting was followed by Limmer [6

Mamangur and Berg 1) presented g senstitving coefficient matrix obtained from the inverse of the Newton Rapneon sacobian matrix. This mathod is based on the assumption that the Jacobian E.2 FARGHAL, SHEBL, and EL-ELA

matrix remains constant during the next operating conditions.
Beside this limitation, the method is not suitable for formulating
the power flow constraints in security constrained dispatch problems using mathematical programming.

Sauer [2] presented a Current Distribution Factors based on the Z-bus formulation with constant swing bus voltage. This method is limited to the application of seneration shift process via the swing generator and does not guarantee with the economic dispatch problem which may require the swing generator to contribute to the load as well as the transmission losses for economic reasons.

Recently, Wai T.Mg [3] presented the so called Generalized Generation Distribution Factors (GGDF) to replace the Generation
Shift Distribution Factors (GSDF). This method is well applicable for cases when the total system generation changes providing that the loads are changed in the same rate at the different loading points. Although stated in his conclusion that his method is suitable to produce optimum generation schedules under security and contingency constraints, it is found through various tests that his conclusion is not completely correct because under security and contingency constraints the power variations in the different loading points are not mecessarily varying in the same rate in large systems and sometimes mose of loads has to be shed under contingency situations.

This power presents a proposed technique with linearized
formula for computing the transmission line power flow in terms of injected power due to any change in power system loading conditions. The formula relates the line power flows to both loads and power generation directly for a transmission network
configuration. Being in an integral form, new power flows on
the lines can be obtained directly without running a complete load flow programs when the total system generation thanges.

MATHEMATICAL PORMULATION

Consider the Z-bus referred to certain bus as a reference bus. This Z-matrix representation can be obtained using the Z-matrix building algorithm [7]. All the shunt impedances in the transmission network are removed and their effect is represented by appropriate injected currents. The general load flow equation can be written as;

> $[v] = [z_{bus}][1]$ (1) ...

where;

 $[v^t] = [v_1 - v_R v_2 - v_R \cdots v_{R-1} - v_R v_{R+1} - v_R \cdots v_N - v_R],$ V_D = reference voltage,

 \mathbf{M} = number of buses.

$$
\left[\mathbf{I}^{t}\right] = \begin{bmatrix} (\frac{s_1^*}{y_1^*} - y_1 V_1) & (\frac{s_2^*}{y_2^*} - y_2 V_2) \dots & (\frac{s_N^*}{y_N^*} - y_N V_N) \\ 0 & (\frac{s_1^*}{y_1^*} - y_1 V_1) \end{bmatrix}
$$

where S^* is the conjugate of the complex power, and V^* is the conjugate of the bus voltage. y_1 = the shunt admittance at bus i.

For a base case operating condition, the current flowing
in a transmission line connecting bus i to bus j can be written **as:**

$$
I_{1j} = (V_1 - V_1) / ZL_{1j} \qquad \qquad \ldots (2)
$$

where ZL, is the primitive impedance of line ij as shown in $Fig.1.$

Substituting eqn. (1) in eqn. (2);

$$
I_{jk} = \sum_{k=1}^{N} [(z_{ik} - z_{jk}) / z_{kj}] I_{k}
$$
 ... (3)

where z_{1k} , z_{jk} are the ikth and jkth entry of the bus impedance matrix referred to the reference bus. I_k is the injected current at bus k including the current flowing in the shunt admittance at this bus. This currect can be given by:

$$
I_k = I_{gk} - I_{Lk} - Y_k V_k
$$

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where; I_{gk} = generation current at bus k ,

 I_{Lk} = load current at bus k .

For an incremental change in the generation current and/or load current and assuming that the change in voltage magnitudes at all buses are very small.

$$
\Delta I_k = \Delta I_{\text{rk}} - \Delta I_{\text{lk}} \tag{5}
$$

Therefore, the corresponding incremental change in line current I_{1j} can be given by;

$$
\Delta I_{1} = \sum_{k=1}^{N} \left[(z_{1k} - z_{jk}) / z_{L_{1}j} \right] \Delta I_{k} \qquad \dots (6)
$$

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For the general application of various security monitoring and control such as generation shift to alleviate the line overloads, generation redispatchrier an incremental loading conditions, the on-line load shedding programs and the estimate
of network power flow due to circuit contingencies, the reference
bus is selected to be a transposed bus to enable the contribution of the slack generator in the incremental change according to the optimization requirements. At the transposed bus, the incremental change in injected current is zero and this is suitable for the assumption that the incremental change in transmission losses is neglected in security monitoring programs.

Using the assumption that the voltage magnitudes are held constants during the incremental active power flow can be given by; Λ

$$
P_{1,j} = v_1 \triangle 1_{1,j}
$$

= $\sum_{k=1}^{N} [(z_{1k} - z_{jk}) / zI_{1,j}] \triangle P_k$... (7)

To obtain a linearized formula relating the incremental change in active power flow due to circuit contingency (outage of line connecting buses p, q) and assuming that the injected
powers at all the buses are kept constant, the recursive bus
impedance matrix [8] is used to modify the bus impedance matrix as; **P**

$$
\[\Delta z\] = \frac{\left[\left[z_{\mathbf{p}}\right] - \left[z_{\mathbf{q}}\right] \cdot \left[z_{\mathbf{p}}\right] - \left[z_{\mathbf{q}}\right]\right]^{\mathbf{t}}}{z_{\mathbf{p}\mathbf{p}} - z_{\mathbf{q}\mathbf{q}} - zz_{\mathbf{p}\mathbf{q}} - zz_{\mathbf{p}\mathbf{q}}}
$$
 ... (8)

where;

 $\left\lceil \mathbb{Z}_p \right\rceil$: $\left[\begin{smallmatrix} Z_q \end{smallmatrix}\right]$ are the pth and qth coulumn vectors of the bus impedance matrix,

 z_{pp} . z_{qq} . z_{pq} are the ppth, gqth and pqth entry of the bus
 $z_{L_{pq}}$ is the self impedance of the removed line.

The incremental change in active power flow due to circuit contingency can be written as;

$$
\Delta P_{1,j} = \frac{\partial P_{1,j}}{\partial z} \Delta z + \sum_{k=1}^{N} \frac{\partial P_{1,j}}{\partial P_k} \Delta P_k \qquad \dots (9)
$$

 $but;$

 $\Delta P_k = 0$ for $k=1,2,\ldots,N$, then;

$$
\Delta P_{11} = (\delta P_{11}/\delta Z) \Delta Z
$$
 ... (10)

Using eqn. (2), we can write;

 $\overline{}$

$$
P_{1,j} = \sum_{k=1}^{N} \left[(z_{1k} - z_{jk}) / z_{L_{1,j}} \right] P_k
$$
 ... (1)

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Taking the partial derivative w.r.t Z;

$$
\Delta P_{13} = \sum_{k=1}^{N} \left[\frac{(\Delta Z_{1k} - \Delta Z_{3k})}{2L_{13}} \right] P_k
$$

 $...(12)$

where ΔZ_{1k} , ΔZ_{jk} are the ikth, jkth entry of the matrix ΔZ ·given in eqn. (8).

APPLICATIONS

Test System

The IEEE 30-bus test system with 6 generators and 41 transmission lines is used to test the accuracy of the proposed formula for linearized power flow applications. Simulations of different cases are made with comparison with a complete load flow, Generalized Generation Distribution Factors (GGDF), and Generation Shift Distribution Factors (GSDF).

Results

Tables 1,2 show the results of applying the proposed technique compared to the Newton-Raphson (N.R) load flow, GSDF, and GGDF, for the percentage change in active power flow in the network for generation shift of 5 MW between generator No.13 'and the slack generator No.1 and and No.8. Table 3 shows the results of applying the proposed techniques compared to the N.R. load flow, GSDF and GGDF for the percentage change in network active power flow due to an increase in load demands at buses 3 , 10, 26, 23, and 29 by 1, 1, 1, 0.5, and 1.5 MW respectively and these loads are supplied by increasing generation at bus shows the results of applying the proposed technique compared to the N.R. load flow, and GGDF for the percentage change in network active power flow due to increasing the load demand at buses 3, 10, 23, 26, and 29 by 1, 1, 1.5, 2, and 2.5 MW respectively and these loads are supplied through increasing the total generation by 8 MW and this increase is distributed among the generators according to the economical dispatch. Table 5 shows the percentage change in network active power
flow, applying the proposed technique compared to the N.R. load
flow, due to the outage of line No.31.

Comments

From tables 1 and 2, the proposed technique is shown to
be accurate as the other existing methods. In case of changing
the load demands, the proposed method is shown to be more accurate compared to the existing linearized techniques. The proposed method is applicable for the case of circuit contingency ecompared to N.R. load flow. As shown in table 5, there is good

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TABLE 1 - Percentage change in active power flow
in case of generation shift between
generator No.13 and the slack generator
No.1.

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TABLE 2 - Percentage change in active power
flow in case of generation shift
between generator No.13 and the
generator No.8

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TABLE 3 - Percentage change in active power
flow in case of changing the load
demand to be compensated by
generator No.13.

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TABLE 4 - Percentage change in active power
flow in case of changing load demand
to be compensated from the different
generators by the economical dispatch.

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TABLE 5 - Change in active power flow
due to outage of transmission
line $No.31$.

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CONCLUSIONS

The paper presents a proposed technique with linearized
, formula for computing the transmission line power flow in terms of injected power due to any change in power system loading conditions. The formula relates the line power flows to both loads and power generation directly for a transmission network * configuration.

The proposed technique is based on the bus impedance matrix and the reasonable assumption of having the system bus voltages constant at 1 p.u. The proposed technique is tested on standard power systems and a comparative study is made with other methods to show the good accuracy of computations during different applications. Each of the other methods is limited to a special case of application, but the proposed formula guarantees a good accuracy in application for the different cases.

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