Improving Voltage Stability of Doubly Fed Induction Generator - based Wind Farm using STATCOM.

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Improving Voltage Stability of Doubly Fed Induction Generator - based Wind Farm using STATCOM

(تحسين استقرارية الجهد لمولد الرياح الحثي ثنائي التغذية باستخدام المعوض التزامني الاستاتيكي)

Iman F.Elzemeity Mohamed F. Kotb, Sahar S. Kaddah and Magdi El-Saadawi

الملخص العربي:-أصبح للطاقة المتجددة مستقبل واعد فى ظل عواقب التغير المناخي فى العقود الأخيرة الذي يجتاح العالم. وتمثل طاقة الرياح نسبة تتجاوز 20% من إجمالى الطاقة المولدة فى دول العالم . و يعتبر مولد الرياح من نوع المولد الحثي ثنائي التغذية Doubly Fed Induction Generator (DFIG) الأفضل بين مولدات الرياح نظرا لكفاءته تحت ظروف سرعات الرياح المتغيرة . الا ان ربط مولدات الرياح للشبكة الكهربية أضاف عدد من التحديات للشبكة الكهربية من بينها استقرارية النظام. تم تحديد مكان DFIG باستخدام القيم الذاتية Eigenvalues ومن ثم اختيار 5 سيناريوهات مختلفة لنسبة طاقة الرياح لاجمالى طاقة النظام. ويمثل ما يعرف بمنحنى القدرة الفعالة و الجهد PV curve كمؤشر لدراسة استقرار الجهد مع زيادة عدد توربينات الرياح من المولد الحثي ثنائي التغذية . حيث وجد ان مع اضافة المزيد من توربينات الرياح يتطلب تعويض للقدرة الغير فعالة Reactive Power Compensation واحدى طرق تعويض القدرة الغير فعالة هو استخدام المعوض التزامني الاستاتيكي STATic synchronous COMpensator (STATCOM) على التوازى مع توربينات الرياح. تمت نمذجة المولد الحثي ثنائي التغذية و المعوض التزامني الاستاتيكى باستخدام برنامج DIgSILENT على نظام 39 نقطة المعتمد من IEEE.

Abstract— **Wind power is one of the most promising renewable resources and Doubly Fed Induction Generator (DFIG) is considered the most cost effective generator for connecting wind power to the grid as it has advantages over other types of wind generators such as operating under variable wind speeds, moderate size of power electronics, and complete control of active and reactive power. But it has consequences on the performance of power system especially power system stability. This paper states the influence of DFIG location on small signal stability using Eigenvalue analysis. Then, Evaluating PV Curve of critical bus as an indicator to state the impact of integrating wind power through DFIG on the voltage stability of power system under different Penetration levels. Besides approving the optimal Mvar for each penetration level to operate the system with wind power in a stable way using trial and error method. The proposed simulation is** tested on IEEE 39 bus test system using DIgSILENT PowerFactory software with five penetration levels of DFIG to examine: 4%, 12%, 21%, 31% and 41%.

I. INTRODUCTION

DOUBLY Fed Induction Generator (DFIG) is presented as the most cost effective wind generator. Adding DFIG to the grid has brought new challenges, one of them is the impact on power system stability. Power system stability has four main categories: voltage stability, frequency stability, rotor angle stability and transient stability. Voltage stability plays an essential issue to determine the maximum penetration level of wind to operate system safely.

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Introducing steady-state model and dynamic model for different technologies of wind turbines has been introduced in [1] and from this studding the influence on voltage stability using PV curve and QV curve. Then using PWM converter to regulate reactive power capability in order to maintain voltage stability limits. In reference [2], sensitivity index is used as an indicator of voltage stability for Doubly-Fed Induction Generators (DFIG) and Fix Speed Induction Generator (FSIG) and comparing the voltage profile for the two different technologies.

Dynamic voltage stability is introduced under different penetration levels of wind energy [3]. After replacing DFIG based wind generators with synchronous generators, the voltage profile changes for the worst case and from this determining the maximum penetration level of wind turbines. Reference [4] states the impact of integrating DFIG on long term of voltage stability based on power capability curve of wind turbine using wind speed and terminal voltage as variables, then estimating the operational limits of DFIG to maintain within voltage stability margin. Where reference [5] studies the impact of DFIG on voltage stability using PSCAD to build the model of DFIG and back-to-back dual PWM inverter for control. The results show that voltage stability decreases with increasing in the numbers of wind turbines and the more the fault distance, the more the increase in voltage stability. It also states that Constant voltage control mode is better than constant power factor control mode for enhancing voltage stability. Reference [6] uses voltage deviation at Critical bus bars as an important index for study voltage stability after integrating wind turbines and under different loading conditions, where reference [7] focuses on the impact of Grid Side Converter (GSC) and Rotor Side Converter on the voltage stability of Point of Common Coupling (PCC). Reference [8] compares Active Power/ Voltage (PV curve) characteristics curve between DFIG and synchronous generator. It also suggests rotor voltage control to regulate the voltage of the system.

Existing of Under Load Tap Changer (ULTC), Generator Over-Excitation Limiter (OXL) in wind power system increases voltage instability [9], Rotor Side Converter (RSC) control method is presented as an effective method to prevent voltage collapse. There are two modes to regulate the voltage of the system: voltage control mode and power factor control mode [10]. Reference [11] introduces a simple method for voltage control by adding capacitor to Exciter Control System of DFIG. Flexible Alternating Current Transmission system (FACTS) such as STATic synchronous COMpensators (STATCOMs) and Static Var Compensators (SVCs) have been used as reactive power compensations to enhance voltage stability [12][13][14]. In Reference [15], the authors compare the voltage profile in case of using STATic synchronous COMpensators (STATCOMs) and Static Synchronous Series Compensator (SSSC), the results show that STATCOM has better influence on enhancing voltage stability.

References [16], [17] and [18] state that STATCOM can adapt with voltage fluctuations due to change of output power of DFIG and variations of wind speed. It enhances the voltage profile of all buses.

This paper introduces a model for STATCOM controller for improving voltage stability of wind power systems, which is installed at the Point of Common Coupling (PCC) of DFIG. Using DIgSILENT PowerFactory software and the simulation is based on IEEE 39-bus system as test system. Estimating PV curve under different penetration level to evaluates the required Mvar of STATCOM for each penetration level.

This paper is organized as follows. In section 2, Problem Formulation. In section 3, the Proposed Algorithm is described in details. Section 4 illustrates IEEE 39-bus system. In section 5, the modeling of STATCOM Controller is described. Section 6 explains the simulation and the results which define the Mvar to install for each penetration level. The conclusion is given in section 7.
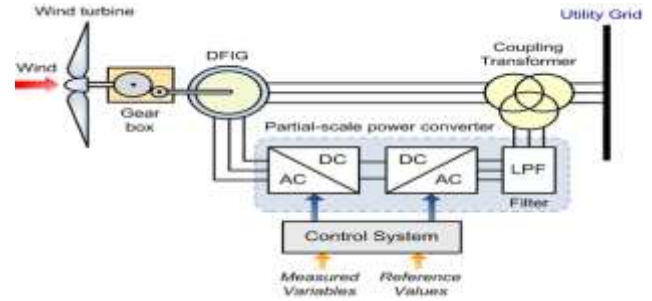
II. **PROBLEM FORMULATION**

Fig.1. Scheme of Wind turbine based DFIG type [19]

DFIG is commonly used as it has the maximum efficiency under different wind speeds over other wind turbine generators as it adds a new challenge to the power system as it is designed to work 30% above and under its synchronous speed. DFIG is a wound rotor type, the stator side is connected to the grid through AC/DC/AC PWM converter and the rotor side is connected to the mechanical part of the wind turbine. The vector control is used to control flow of active power and reactive power between the stator and the grid as shown in Fig. 1.

The DFIG mathematical modelling as described in d-q frame [21] as following fellow and as shown in Fig. 2:

$$V_{ds} = R_s I_{ds} + \frac{d}{dt}(\Psi_{ds}) - \omega_e \Psi_{qs} \tag{1}$$

$$V_{qs} = R_s I_{qs} + \frac{d}{dt}(\Psi_{qs}) + \omega_e \Psi_{ds} \tag{2}$$

$$V_{dr} = R_r I_{dr} + \frac{d}{dt}(\Psi_{dr}) - (\omega_e - \omega_r)\Psi_{qr} \tag{3}$$

$$V_{qr} = R_r I_{qr} + \frac{d}{dt}(\Psi_{qr}) - (\omega_e - \omega_r)\Psi_{dr} \tag{4}$$

The stator flux linkages:
$$\Psi_{ds} = L_s I_{ds} + L_m I_{dr} \tag{5}$$
$$\Psi_{qs} = L_s I_{qs} + L_m I_{qr} \tag{6}$$
The rotor flux linkages:
$$\Psi_{dr} = L_s I_{ds} + L_m I_{ds} \tag{7}$$
$$\Psi_{qr} = L_r I_{qr} + L_m I_{qs} \tag{8}$$

The generated torque:

$$T_e + T_{turbine} = J\frac{d}{dt}\omega_m + B\omega_m \qquad (9)$$

Where: Te = Electromagnetic torque, J =   Inertia of rotor , ωm = Mechanical speed.

DFIG electromagnetic torque:

$$T_e = \frac{3}{2}\frac{P}{2}L_m(I_{qs}I_{dr} - I_{ds}I_{qr}) \qquad (10)$$

DFIG active power and reactive power:

$$P = V_{ds}I_{ds} + V_{ds}I_{qs} \qquad (11)$$
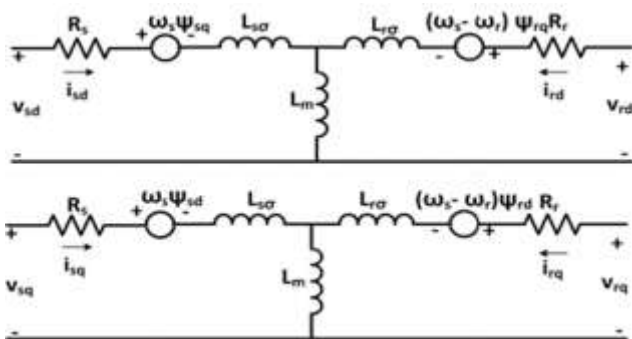$$Q = V_{qs}I_{ds} - V_{ds}I_{qs} \qquad (12)$$

Fig.2. Equivalent circuit of DFIG in the d-q axis reference [20]

DFIG can operate around ± 30% the synchronous speed which causes fluctuations in output power represented in what is called Power/Wind speed characteristics curve as shown in Fig. 3[21]. There are three wind speeds to identify Power/Wind speed characteristics curve: Cut-in wind speed which is represented the minimum wind speed the DFIG can operate, Cut-out wind speed which is presented the maximum wind speed the DFIG can operate and the nominal wind speed in which DFIG reaches its maximum efficiency. As shown in Fig. 3, there are four zones in Power/Wind speed characteristics curve. The first and the fourth zones are represented the zones in which DFIG cannot operate. Zone 2 represented the operation with maximum power coefficient Cpmax where Zone 3, the DFIG generates its rated output power. The mathematical equations of wind turbine mechanical output are expressed by the following:

$$P_{aero} = 0.5\rho AC_p v^3 \qquad (13)$$

$$C_p = f(\lambda,\beta) = 0.5\left(\frac{116}{\lambda_i} - 0.4\beta - 5e^{-21/\lambda_i}\right) \qquad (14)$$

$$\frac{1}{\lambda_i} = 1/\left(\frac{1}{\lambda+0.8\beta} - \frac{0.035}{\beta^3}\right) \qquad (15)$$

$$\lambda = \frac{W_T R}{v} \qquad (16)$$

The aerodynamic torque: $P_{aero} = 0.5\rho AC_p v^3$ $\qquad (17)$

Where: ρ: the density of air=1225 kg/m3, Cp: the power coefficient, v: the wind velocity (m/s), β: the bitch angle, R: the radius of the turbine blades (m), A: the cross section area of the WTG (m2), λ: tip speed ratio, WT: the speed of wind turbine rotor (rad/s).

Due to the variations in output power of DFIG and stochastic wind speeds, the fluctuations of voltage profile increases with increase the sizing of wind generators in the system. In this paper, the locations of DFIG based on replacing

the same MW of synchronous generator with DFIG. Sorting the possible locations in ascending order according to Electromechanical Oscillations which has a range of 0.2-2 Hz [22] using Eigen Value analysis.   Eigen value consists of two parts: real part known as σ and imaginary part. The more σ is negative, the more the system is stable.
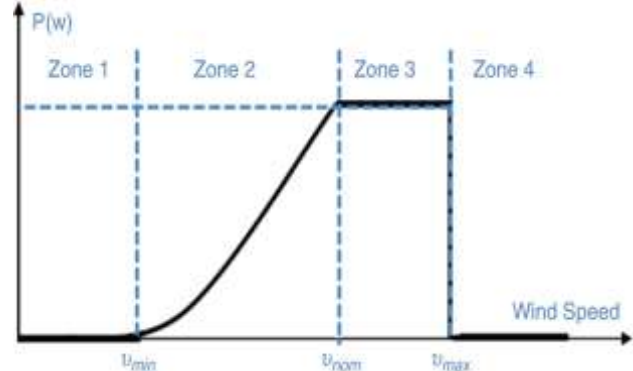

Fig.3. Wind turbine power characteristics curve [22]

III.   THE PROPOSED ALGORITHM

The paper estimates the location of DFIG based on Eigenvalue analysis, then determines the available penetration levels at the predefined locations and studding the voltage profile of the critical bus of the test system which is defined as the weakest point in the system and the highest sensitivity to voltage fluctuations .To estimate voltage profile of critical bus, PV curve which is used to state the maximum MWs for the bus load to prevent voltage collapse and then evaluate if the system is stable or unstable as shown of Fig.4. Where V is the voltage of the critical bus and P is the total active power of the load. The aim of this paper is to evaluate the required Mvar of STATCOM as a reactive power compensation for different penetration levels of DFIG in order to improve voltage profile of the system.
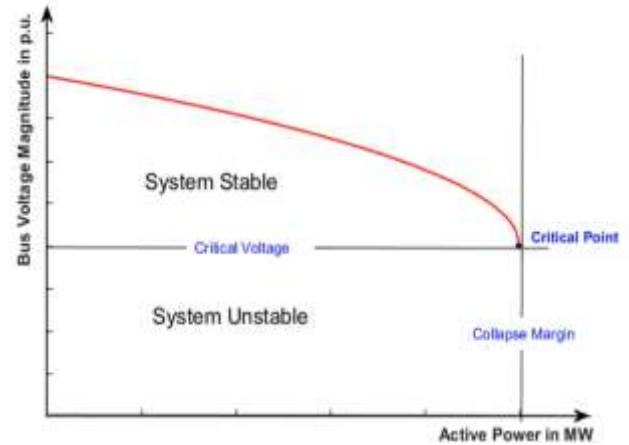

Fig.4. P-V curve of the critical bus to determine voltage stability

There are seven steps for this proposed algorithm to be summarized as following:

Step 1: Build the test system without the presence of DFIG.

Step 2: State the permissible locations to install DFIG based on Electromechanical Oscillations results using Eigen Value method.

Step 3: Evaluate the penetration levels of wind generators depending on the predefined locations.

Step 4: Define the critical bus in the test system.

Step 5: Estimate PV curve of the critical bus under different penetration levels and define the MW Collapse margin for each case.

Step 6: Using STATCOM as a reactive power compensation to improve MW Collapse margin based on trial and error method.

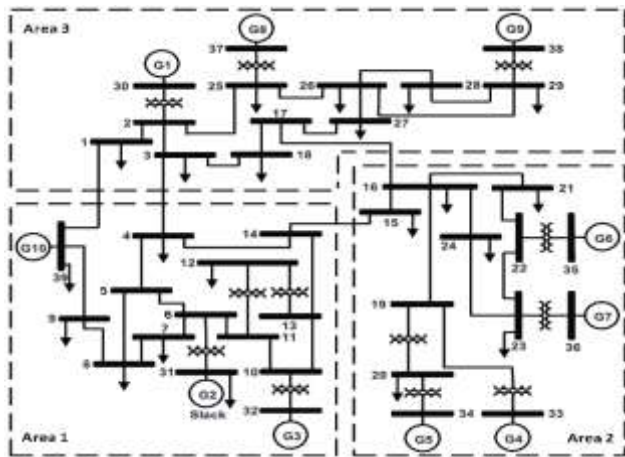Step 7: Compare the Mvar required for each penetration level to reach the MW Collapse margin of the original system.

Fig. 5. New England test system [24]

IV. TEST SYSTEM DESCRIPTION

IEEE 39 bus system which is known as New England Test System is consists of three areas and 10 Synchronous generators as shown in Fig.5 and Appendix A and is operating at 60 Hz [23]. "Gamesa G97 2 MW" is presented the type of DFIG which is used in this paper. The details of model are show in Appendix B.
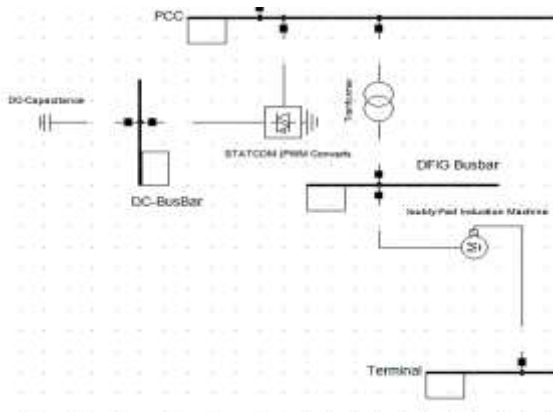

Fig. 6. STATCOM connection with DFIG at PCC point of DFIG

V. STATCOM MODELING

STATCOM, in this paper consists of series DC storage capacitance and pulse width modulation (PWM) which is connected to the point of common coupling (PCC) of DFIG as shown in Fig.6.

VI. SIMULATION AND RESULTS

The Simulation has been carried out using DIgSILENT PowerFactory software in three stages: determine the locations and penetration levels of DFIGs, evaluate PV curve for each penetration level and compare it with the original test system and adding STATCOM to each DFIG at the point of PCC and from here estimating the Mvar required for each penetration level of DFIG.

A. Determining Location and Penetration Levels of DFIG

Location of wind farm has more factors than stability analysis. It can be onshore or offshore, for example offshore wind turbine requires between 10 to 30 meter for water height and Onshore wind energy requires identifying wind power class, cut-in speed and the average wind speeds should be above 8.5 m/s. The locations of DFIG based on replacing the same MW of synchronous generator with DFIG. Sorting the possible locations in ascending order according to Electromechanical Oscillations which has a range of 0.2-2 Hz using Eigen Value analysis. Eigen value consists of two parts: real part known as σ and imaginary part. The more σ is negative, the more the system is stable. By replacing the ten synchronous generators with DFIGs, replacing one at a time and define the σ of the Eigen value for each replacing using QR/QZ method in DIgSILENT. The results as shown in TABLE.I indicate that the best five locations with less electromechanical oscillations are by replacing the synchronous generators with DFIGs at buses 30, 37, 31, 32 and 36 respectively. And from the predefined locations for replacing synchronous generators with DFIGs, the five penetration levels of this paper are estimated as shown in TABLE.II

TABLE I
EIGEN VALUE ANALYSIS AFTER REPLACING SYNCHRONOUS
GENERATORS WITH DFIGS AT THE TEN DIFFERENT LOCATIONS

DFIG Location at Bus No	Real Part σ_{min}
Bus 30	-0.35184644231
Bus 37	-0.31141461947
Bus 31	-0.30764785798
Bus 32	-0.28324202251
Bus 36	-0.28149419694
Bus 38	-0.28080568898
Bus 35	-0.27920623193
Bus 34	-0.2780181199
Bus 33	-0.2662592786
Bus 39	-0.25063543822

TABLE II
MVAR REQUIRED FROM STATCOM FOR 4%, 12% AND 21%
PENETRATION LEVELS OF DFIG

DFIG Penetration Level %	DFIG Locations	Replacing MW
First Penetration Level 4%	Bus 30	Replacing the 250 MW SG at bus 30 with DFIG
Second Penetration Level 12%	Bus 30 Bus 37	Replacing the 250 MW SG at bus 30 and the 540 MW SG at bus 37 with DFIGs
Third Penetration Level 21%	Bus 30 Bus 37 Bus 31	Replacing the 250 MW SG at bus 30, the 540 MW SG at bus 37 and the 520 MW SG at bus 31 by DFIGs
Fourth Penetration Level 31%	Bus 30 Bus 37 Bus 31 Bus 32	Replacing the 250 MW SG at bus 30, the 540 MW SG at bus 37, the 520 MW SG at bus 31 and the 650 MW SG at bus 32 by DFIGs
Fifth Penetration Level 41%	Bus 30 Bus 37 Bus 31 Bus 32 Bus 36	Replacing the 250 MW SG at bus 30, the 540 MW SG at bus 37, the 520 MW SG at bus 31, the 650 MW SG at bus 32 and the 560 MW SG at bus 36 by DFIGs

B. Evaluating PV Curve for Each Penetration Level of DFIG

PV curve is evaluated using DIgSILENT PowerFactory software at the critical bus of the test system as shown in TABLE.III. The critical bus in IEEE 39 Bus system is bus 12 [26].The results show that the system is slightly influenced by increasing the penetration levels 4% and 12%, but in case of 21% the collapse margin reduces 14.3% from its original value and for high penetration levels 31% and 41% of DFIG, collapse margin decreases by 61% and 64% respectively.

TABLE III
COLLAPSE MARGIN FOR 4%, 12%, 21%, 31% AND 41%
PENETRATION LEVELS OF DFIG

Penetration Level of DFIG %	Collapse Margin (MW)
Original System	68.795249
4%	68.267248
12%	59.903251
21%	28.055250
31%	25.955250
41%	68.795249

C. Estimating the required Mvar for Each Penetration Level of DFIG

Using trial and error method for 4%, 12%, 21%, 31% and 41% penetration levels of DFIG to calculate the required Mvar of STATCOM compensation to restore the voltage stability margin to reach 69 MW collapse margin as in the original system. The results show that as in TABLE.IV, the Mvar required for 4%, 12%, 21%, 31% and 41% penetration levels of DFIG are 185 Mvar, 234 Mvar, 738.7 Mvar, 1417 Mvar and 1498 Mvar respectively. The STATCOM is connected to the PCC point of the DFIG.

TABLE IV
MVAR REQUIRED FROM STATCOM FOR 4%, 12%, 21%,
31% AND 41% PENETRATION LEVELS OF DFIG

Penetration Level of DFIG %	Collapse Margin (MW)
4%	185 Mvar at DFIG at Bus 30
12%	185 Mvar at DFIG at Bus 30 49 Mvar at DFIG at Bus 37
21%	185 Mvar at DFIG at Bus 30 49 Mvar at DFIG at Bus 37 504.7 Mvar at DFIG at Bus 31
31%	185 Mvar at DFIG at Bus 30 49 Mvar at DFIG at Bus 37 504.7 Mvar at DFIG at Bus 31 678.3 Mvar at DFIG at Bus 32
41%	185 Mvar at DFIG at Bus 30 49 Mvar at DFIG at Bus 37 504.7 Mvar at DFIG at Bus 31 678.3 Mvar at DFIG at Bus 32 81 Mvar at DFIG at Bus 36

VII. CONCLUSION

In this paper, the locations of DFIGs has been determined based on Eigenvalue analysis and from this inducing five penetration levels of DFIG to examine which are 4%, 12%, 21%, 31% and 41%. Using PV curve as an indicator of voltage stability at the critical bus of the test system which is bus 12 in IEEE 39 bus system, then determine the MW Collapse margin for each penetration level of DFIG. The results show that the system is slightly influenced by the increasing in penetration levels 4% and 12%, but in case of 21% the collapse margin reduces 14.3% from its original value and for high penetration levels 31% and 41% of DFIG, collapse margin decreases by 61% and 64% respectively. The Mvar required from STATCOM compensation for different penetration levels of DFIG has been evaluated and tested on IEEE 39 Bus system. The methodology of evaluating the Mvar required for each penetration level in order to reach the MW Collapse margin of the original system before integrating DFIG to the grid is based on trial and error method. The results show that the Mvar required for 4%, 12%, 21%, 31% and 41% penetration levels of DFIG are 185 Mvar, 234 Mvar, 738.7 Mvar, 1417 Mvar and 1498 Mvar respectively. Simulation has been carried out using DIgSILENT PowerFactory software.

Appendices

APPENDIX B
DATA OF GAMESA G97 2 MW

Data Sheet	Value
Rated power	2,000.0 kW
Cut-in wind speed	3.0 m/s
Rated wind speed	11.0 m/s
Cut-out wind speed	25.0 m/s

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